





Testing instrument capabilities from simulations

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INAF - Osservatorio Astronomico di Torino

Gaia - ELSA conference, Sèvres, 7-11 June 2010

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Testing instrument capabilities from simulations

• Simulation of the Instrument







Testing instrument capabilities from simulations

- Simulation of the Instrument
- Simulated Instrument vs. Real Instrument







Testing instrument capabilities from simulations

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- Simulated Instrument vs. Real Instrument
- Methods for testing capabilities







Testing instrument capabilities from simulations

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- Simulated Instrument vs. Real Instrument
- Methods for testing capabilities
- example: astrometry







Instrument simulation in CU2 - overview









Data generators characteristics vs. Instrument model

• GIBIS: simulation of data at pixel level. As realistic as possible for limited regions of the sky and over short periods of time.

• GASS: simulation of telemetry stream. Use simplified models of the instrument. Large amount of data over a significant part of the planned Gaia mission duration

• GOG: simulation of observed object lists + intermediate/end of mission Gaia data for given source. Use error models.

-> Need different models of the same subsystems/effects (problems: duplication and consistency)







Simulated vs. Real Instrument

- instrument is not completely built yet
- many subsystems already tested or being tested now
- In any case, knowledge of the real instrument can/will be only partial:
 - Many relevant instrument parameters not measured (or nonmeasurable) on-ground
 - In-flight configuration and environmental conditions different from nominal / predicted ones.







Simulated vs. Real Instrument









Further note on on-ground measurements

- Usually made by industry to convince ESA that requirements are fulfilled
- Requirement fulfilled doesn't mean "proper" knowledge of the instrument
- Example: CCD non-linearity
- Req may sound like "CCD non-linearity calculated in someway shall not exceed 1%"
- For calibration purposes, you may prefer a non-linearity > 1%, but a well known non-linearity profile vs. integration time







Further note on on-ground measurements



integration time







Evaluation methods









Evaluation methods









Example: astrometric performance







PSF/LSF model for simulations

The model is based on a dual representation:

- numerical library for GIBIS. The starting point is a numerical library where the elements are generated from the optical design of the instrument (CodeV generated WFEs, 1 per CCD) plus some ad-hoc effects (TDI, pixel, etc).
- analytical library for GASS/GOG. The elements of the library are generated from bi-quartic B-spline fittings of the numerical library. Interpolation for any point in the coefficients grid available.
- Both the analytical and the numerical representations provide the integrated flux over one pixel, normalised to the total integrated flux







Note that:

• many effects can be introduced at the level of the numerical library and they will automatically be present in the analytical representation with no need to develope specific models for GASS/GOG

 the analytical representation requires a minimised number of computations in GASS/GOG

 nonetheless, many effects are not usefully described by means of precomputed libraries (CTI, noise, magnitude, non-linearity/ saturation, ...) and are treated separately







PSF Numerical (discrete sampling) Library

Generated as follows (starting from nominal WFEs, PS-010):

- monochromatic PSFs (250-1050 nm) with steps of 1 nm
- 11 quasi-monochromatic PSF (using triangular bands, LL-080)
- pixel, TDI, attitude errors, optical distortion, charge diffusion (effqmPSF)
- source motion and gates are treated separately
- Polychromatic PSF can be computed by linear combination of effqmPSF + source spectrum
- Polychromatic PSF library for colour index V-I also available.







Analytical library

Analytical library:

• Fitting functs: Bi-quartic B-Spline + wings (LL-066). Result: Analytical function giving pixel readout for any (continuous) AL position (33 params)

- \cdot Details of the analytical library coeffs calculation in DB-009
- Interpolation in coefficients space domain (DG-014)

Parameter	SM	AF	
Telescopes	2	2	Cize of Denometer space domain
FoVs	7	62	<- Size of Parameter space domain
Triang. bands (wavelength)	11	11	
(V-I)	12	12	
	154	1364	

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Analytical model - AF (example)



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Other talks related to instrument modeling

- F. van Leeuwen Modeling the attitude: lessons learnt from Hipparcos
- D. Risquez Modeling the attitude of the Gaia Satellite
- M. Weiler Implementation of CTI models in GIBIS
- T. Prod'homme Radiation effects on Gaia CCDs







LSF - Signal profile modeling

- Problem treated in LL-084, MG-009
- The LSF model can be written as a linear combination of basis functions

$$\widetilde{L}(u) = \sum_{m=0}^{N} c_m B_m(u)$$

• How many parameters N do we need to properly model the signal profile?

• Which are the basis functions that provides the most accurate approximation of the LSF?

• How good this approximation is (as a function of N)?







LSF - Signal profile modeling

Principal Component Analysis provide a solution to this problem (LL-084)

- The model of the signal profile is obtained starting from a large sample of LSFs, generated with many different WFEs and SEDs over M points
- Any LSF can be written as linear combination of basis vectors

$$\vec{L} = c_0 \vec{B}_0 + \sum_{m=1}^{M} c_m \vec{B}_m$$

where B_0 is the mean LSF and B_m are obtained from the covariance matrix (deviations wrt the mean profile)

The truncated expansion $LSF' = c_0B_0 + \sum_{m=1}^{N < M} c_mB_m$ has minimum expected RMS error among all linear models with N free parameters (under proper hypothesis)







LSF - Signal profile modeling

Another approach is also proposed (MG-009):

signals are expected to be reasonably close to the ideal case -> they fit a context of small perturbations/aberrations

$$F_0(u;\lambda) = \left(\frac{\sin\rho}{\rho}\right)^2, \quad \rho = \frac{\pi D}{\lambda f}u$$

• perturbations ->
$$F_n(u;\lambda) = \frac{d}{du}F_{n-1}(u;\lambda) = \frac{d^n}{du^n}F_0(u;\lambda)$$

• polychromatic LSF ->
$$F_0(u) = \int S(\lambda)F_0(u;\lambda)d\lambda$$

$$\sum_{k} F_{p}(u_{k}) F_{q}(u_{k}) = \delta_{pq}$$







LSF - basis functions



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Signal profile modeling - summary

LL-084	Model	MG-009
~ 10 - 11	Number of params	~ 10 - 11
PCA (mean LSF + cov. + interpolation)	Basis functions	(sinx/x)² + derivatives
10-3	RMS residual (5 pars)	
10-4	RMS residual (10 pars)	10-4
	astrom. residual (µ,rms)	(7 µas ;<1 µas)
Tukey's biweight (LL-068)	Localisation process	COG
simulated + real (camp. #3)	Data	simulated







Astrometric accuracy

- First tests with this models (Analytical LSF + PCA) in IDT 8.0
- Other independent astrometric accuracy analysis:



• Similar results in the magnitude range [6,14]







Summary

• Simulation of the instrument must take into account all major effects

• Effects introduced with rather simple models may already provide a satisfactory first order description

- Further refinements using more complex/sophisticated models fight with:
 - "distance" between the nominal and the real instrument
 - Computing time, data storage, et cetera

• Requirements satisfied does not mean you are able to properly model/simulate your instrument

• Tests of instrument capabilities using simulations are reliable only up to a certain level (they provide anyway a first approximation of what you can expect)

 \cdot Gaia astrometric performances will probably be limited by poor knowledge of the real signal profile







Thank you

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