# Inverse methods for asteroid orbit computation.

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# Asteroid orbital inverse problem

 $y \in \Re^m$  the measurements  $x \in \Re^d$  the unknown parameters

To interpret the measurements we need to solve the inverse problem for x:

$$y = f(x) + \epsilon \tag{1}$$

The Bayesian solution:

$$p(x \mid y) = \frac{p(x)p(y \mid x)}{\int p(x)p(y \mid x)dx}$$
(2)

The posterior distribution combines a priori information p(x) and the measurement likelihood p(y | x).

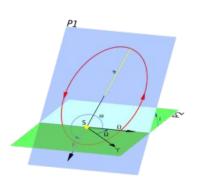


Figure: a - size of the orbit, e - describing the flatness, i - inclination with respect to the reference plane  $\Omega$  - horizontally orients the ascending node, with the reference frame's vernal point,  $\omega$  - an angle measured from the ascending node to the semimajor axis. M - defines the position of the orbiting body along the ellipse at a specific time (the "epoch").

The Bayesian a posterior p.d.f. of the orbital elements is given by:

$$p_{p}(\mathbf{P}) = C p_{pr}(\mathbf{P}) p_{\epsilon}(\Delta \Psi(\mathbf{P})), \quad (3)$$

- $p_{pr}(\mathbf{P})$  is the a priori p.d.f.
- *p<sub>ϵ</sub>*(ΔΨ(**P**)) is observational error p.d.f., evaluated for the observed minus computed (O-C) residuals ΔΨ(**P**)
- $C = (\int p(\mathbf{P}, \Psi) d\mathbf{P})^{-1}$  is the normalization constant
- $p(\mathbf{P}, \Psi) = p_{pr}(\mathbf{P})p_{\epsilon}(\Delta \Psi(\mathbf{P})).$

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# MCMC ranging

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## Markov-Chain Monte-Carlo ranging (MCMC):

- Choose two observations A and B from \u03c6. Pick pt for the topocentric spherical coordinates at the two observation dates A and B (e.g simple 6D gaussian in spherical coordinates phase space = complicated pt in orbital-elements phase space)
- Propose new candidate orbit with the help of proposal densities,
- Accept or reject the orbit as a new sample, based on a<sub>r</sub>

$$a_r = \frac{p_p(\mathbf{P}')}{p_p(\mathbf{P}_t)} \frac{p_t(\mathbf{Q}_t, \mathbf{Q}')J_t}{p_t(\mathbf{Q}', \mathbf{Q}_t)J'}, \qquad (4)$$

where J' and  $J_t$  are the determinants of Jacobians from topocentric coordinates to orbital parameters for the candidate and the last accepted sample, respectively. Acceptance criteria:

$$\begin{array}{ll} \text{If } a_r \geq 1, & \text{then } \mathbf{P}_{t+1} = \mathbf{P}'. \\ \text{If } a_r < 1, & \text{then } \begin{cases} \mathbf{P}_{t+1} = \mathbf{P}', \text{ with probability } a_r, \\ \mathbf{P}_{t+1} = \mathbf{P}_t, \text{ with probability } 1 - a_r. \end{cases}$$

Repeat many times to reach the stationary distribution.

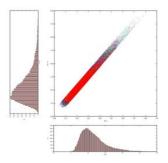


Figure: Distribution of ranges for the 2009  $DD_{45}$ , assuming 2.0 arcsec observational error. Colors correspond to different Markov chains.

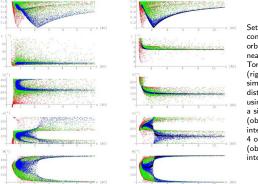
## Convergence diagnostics

relates to the idea that Markov chain after sufficient number of iterations will eventually converge to the stationary distribution (target distribution), starting from any point in the phase-space and then mix in that phase-space forever.

## Other convergence diagnostics based on:

- Different approaches single vs. many chains
- Shrink factor (Gelman and Rubin, 1992)
- Autocorrelation function
- Running means of parameters (Gewke, 1992)
- Marginal probability plots
- Others (comparative review can be found in e.g. Cowles and Carlin, 1996)

# Applications and examples



Sets of distributions each composed of 5000 possible orbit solutions for the near-Earth objects (1685) Toro (left), (4) Vesta (right) obtained from simulated Gaia data. The distributions were obtained using 3 observations from a single scan (observational time interval of 0.25 d) - Toro, 4 observational (observational time interval of 0.32 d) - Vesta.

Image: A image: A

More in: "Asteroid orbits with Gaia using Markov-Chain Monte-Carlo ranging", D.Oszkiewicz, K.Muionen, J.Virtanen, M.Granvik, 1st IAA Planetary Defense Conference: Protecting Earth from Asteroids, proceedings. We contribute to the Gaia processing pipeline - CU4/DU456.

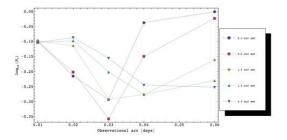


Figure: Time evolution of collision probabilities for 2008 TC<sub>3</sub> using MCMC ranging generated orbits with Jeffreys apriori (n-body approach).

Nr. of	Noise	MCMC
obs.	[arcsec]:	ranging:
	100 - 10 - 10 - 10 - 10 - 10 - 10 - 10	Jeffrey's apriori
2	0.3	0.80 (15281)
	0.5	0.79 (15114)
	1.0	0.80 (14584)
	1.5	0.79 (13991)
	2.0	0.79 (13585)
3	0.3	0.61 (2813)
	0.5	0.63 (3271)
	1.0	0.77 (6025)
	1.5	0.80 (8412)
	2.0	0.82(12113)
4	0.3	0.51 (14960)
	0.5	0.44 (7878)
	1.0	0.51(4742)
	1.5	0.63 (6116)
	2.0	0.70 (8678)
5	0.3	0.92 (44053)
	0.5	0.71 (28966)
	1.0	0.53 (12620)
	1.5	0.53 (9611)
	2.0	0.57 (8930)
6	0.3	$\approx 1.0 (49771)$
	0.5	0.95 (46079)
	1.0	0.69 (27786)
	1.5	0.59 (16348)
	2.0	0.56 (11939)

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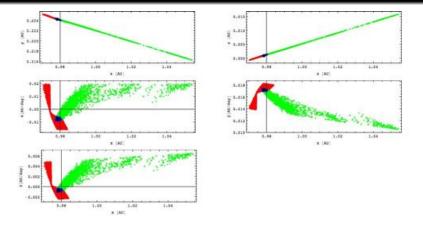


Figure: (a) Green - marginal distribution of orbital elements obtained for asteroid 2008 TC3 using 5 observations and 0.5 arcsec noise assumption. Blue - orbits leading to a collision with the Earth from the green set. Red - orbits leading to a collision with Earth obtained using 3 observations and 2.0 arcsec astrometric noise assumption.

(b) (4) (2) (4)

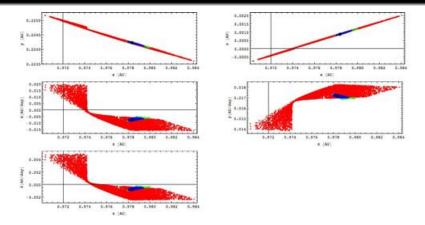


Figure: (b) Green - marginal distribution of orbital elements obtained for asteroid 2008 TC3 using 6 observations and 0.3 arcsec noise assumption. Blue - orbits leading to a collision with the Earth from the green set. Red - orbits leading to a collision with Earth obtained using 3 observations and 2.0 arcsec astrometric noise assumption.

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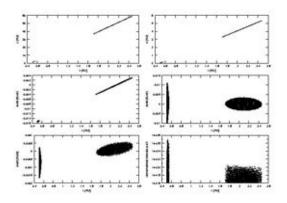


Figure: Cartesian orbital-element PDF for 2003 WW<sub>188</sub>. Although a TNO solution is possible, an NEO solution is more likely. However, since the observational time span is only about three days and the number of observations is three, one should not draw too definite conclusions either way.

Summary:

- We have developed novel variants of asteroid orbit computation methods that map the extensive volume of solution space.
- Distribution of O-C residuals could be used as outlier detection criteria.
- These methods can also be useful in other problems like computing collision probabilities, dynamical classification, performing the recovery of lost objects.

## Poster number 15!

## Asteroid spin and shape inversion for simulated Gaia photometry Dagmara Oszkiewicz1, Karri Muinonen12 and Tuomo Pieniluoma

Shape



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tries. Here we apply Markov-chain Monte-

### MCMC sampling

We make use of general convex shapes de-

## Simulated Gaia photometry

### (21) Lutetia data

Here we make use of the 26 lightcurves, making the total of 1326 photometric ob-servations over a period of 35 years 3

Above: Original shape used to simulate Gaia data. Below: Shape inverted from



Below: Shape inverted from the phototia using convex stochastic optimization.



Rotational period and pole sion for the simulated Gaia data. Original spin parameters: rotation period 10.17395622 h, tational phase 110.1 deg.





Below: Rotational period and pole distributions around one of the possible poleobtained from MCMC convex inversion for asteroid (21) Lutetia. Here we used We utlize a pro-dimensional proposal with mean 1.0 deg and standard deviation





Tappa et al. [3] list two pole solutions for (21) Lutetix β<sub>1</sub> = +3 deg, λ<sub>1</sub> = 39 deg, β<sub>2</sub> =

## Conclusions

We have applied convex stochastic optimization and MCMC inversion methods to derive asteroid spins and shapes using simulated Gaia photometry. The original and inverted shapes are overall in cood aresenser. The local features are not reflected in the inverted shape. MCMC asteroid

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