

Radial and rotational velocity determination by minimum distance method

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With thanks to Yves Frémat for the inspiration

GWP-S-650-10000 Radial and rotational velocity with minimum distance method

First solution

Input:

- Grid of template spectra (T_{eff} , $\log g$, other params), very high resolution
- T_{eff} , $\log g$, other params (determined by CU8) so we can select the template spectrum
- Observed spectrum: λ_i , f_i , error information
Noise filtering?

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Algorithm:

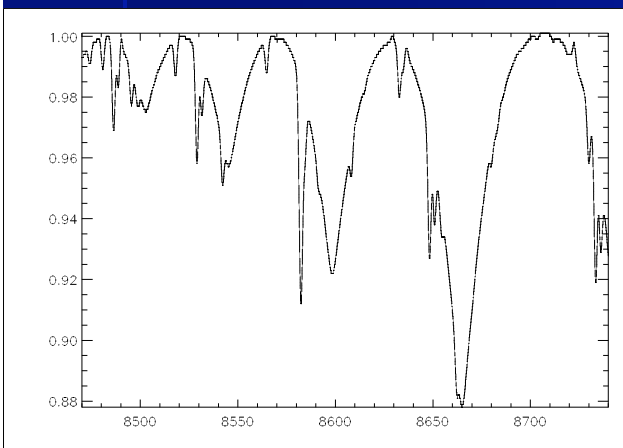
- For a number of trial v_{rad} , for a number of trial $v \sin i$:
 - “shift” the template spectrum: $F(\Lambda (1 + v_{\text{rad}}/c))$
 - Convolve with rotational broadening ($v \sin i$)
 - Convolve with instrumental profile
 - Rebin to simulate RVS instrument $\Rightarrow F'(\lambda_i)$
 - $\sigma^2 = \sum (F'(\lambda_i) - f_i)^2$
- Determine v_{rad} , $v \sin i$ that give smallest σ
- Convert to barycentric velocity
- Determine error on this result

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Comments on first solution:

- Efficiency: log Λ alternative
resampling of observed spectrum: additional noise
- Optimize search of minimum sigma



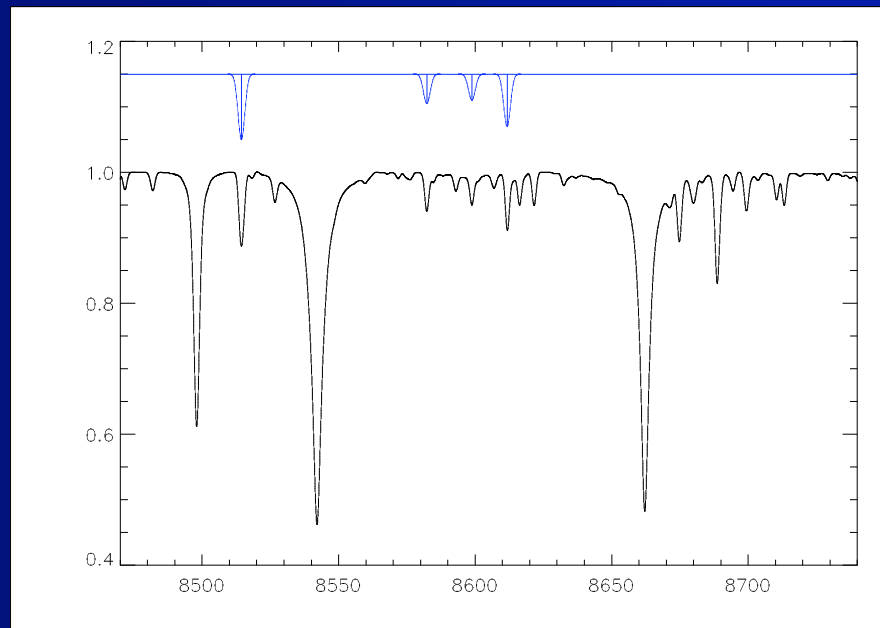
Obtaining the correct solution:

- Spectral lines used to determine T_{eff} , log g are not necessarily the best to determine v_{rad} , $v \sin i$:
Select one / a few spectral lines / use weights

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Second solution: Least Squares Deconvolution

Donati et al. (1997)



Least Squares Deconvolution

Input:

- T_{eff} , $\log g$, other params (determined by CU8)
so we can select the appropriate mask
- Mask
- Observed spectrum: λ_i , f_i , error information
Noise filtering?

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Algorithm:

- Try “broadening” function
Gaussian \otimes rotational broadening ($v \sin i$)
- Try v_{rad} shift
- Best fit of template to observed spectrum

Further refinement:

- Adjust depth of spectral lines + redetermine fit

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Advantage first solution:

- simplicity

Advantages second solution:

- Selection of spectral lines that are useful in determining v_{rad} and $v \sin i$
- Adjusting depth of line improves on model spectra

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- V_{rad} affected by stellar winds
E.g. hot stars: computer codes can include effect of a stellar wind; can influence symmetry of hydrogen lines
- $V \sin i$ affected by non-sphericity of stars
E.g. Be stars: “true” $v \sin i$ could be larger than the measured one. Non-spherical Be models could be used as template spectra
- Should we go for the most sophisticated model for each type of star, or is consistency across HR diagram more important?

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Development plan:

- Cycle 2: implement first solution (inefficient form)
 - Algorithm does not need a lot of development
 - Concentrate on Java issues / interface other WPs
- Later cycles: implement second solution
 - Use first solution as a reference point
 - Hopefully some masks available then

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