

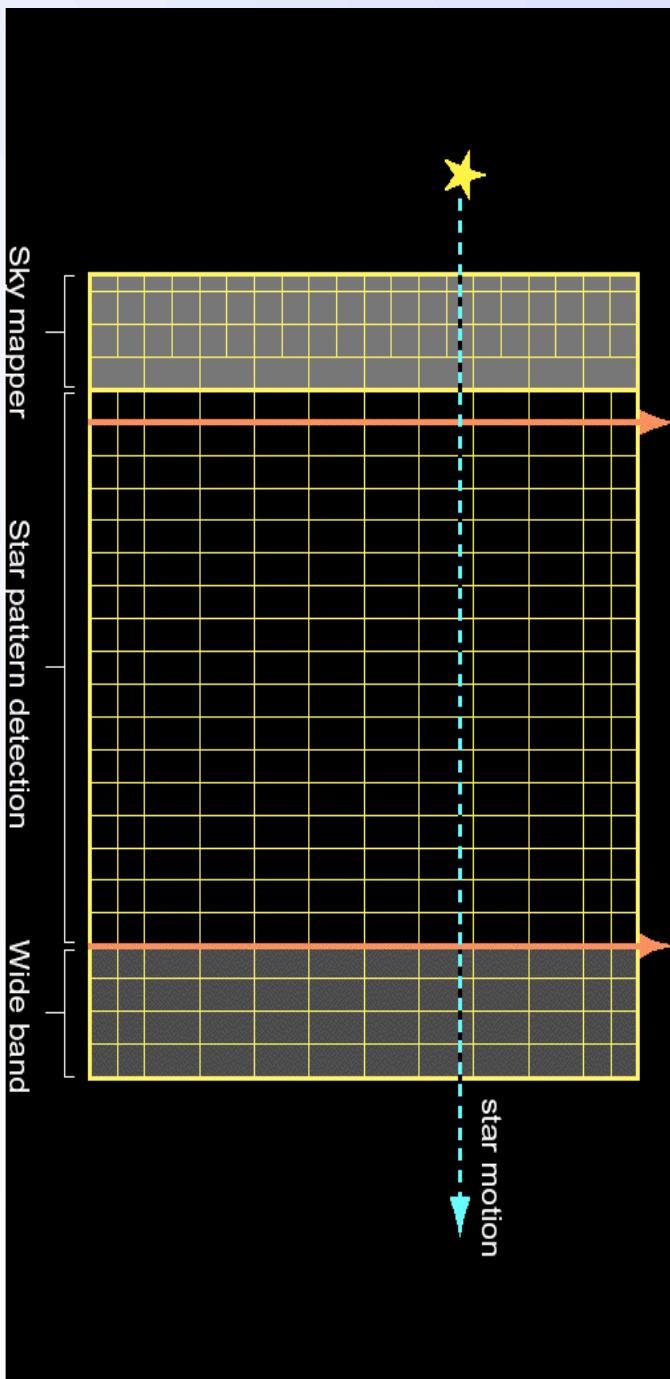
Plan

- General presentation
- The focal plane
- Requirements for detection and selection
- Needs for the PDHE
- Simulations
- Overview of processing in GIBIS
- Interface with PDHE study



Many ways to describe the astro focal plane

- Science (function):
 ASM (detection) AF (astrometry)
 ASMO/1 (all read) BBP (photometry)
- Sampling (electronics):
 ASM (2x2) ASMO3+AF+BBP (selected)
- Patches (telemetry):
 - all differents!
 - AF01-16 (6x8) AF17
 - BBP
- Activation:
 ASM2(redundancy) all others



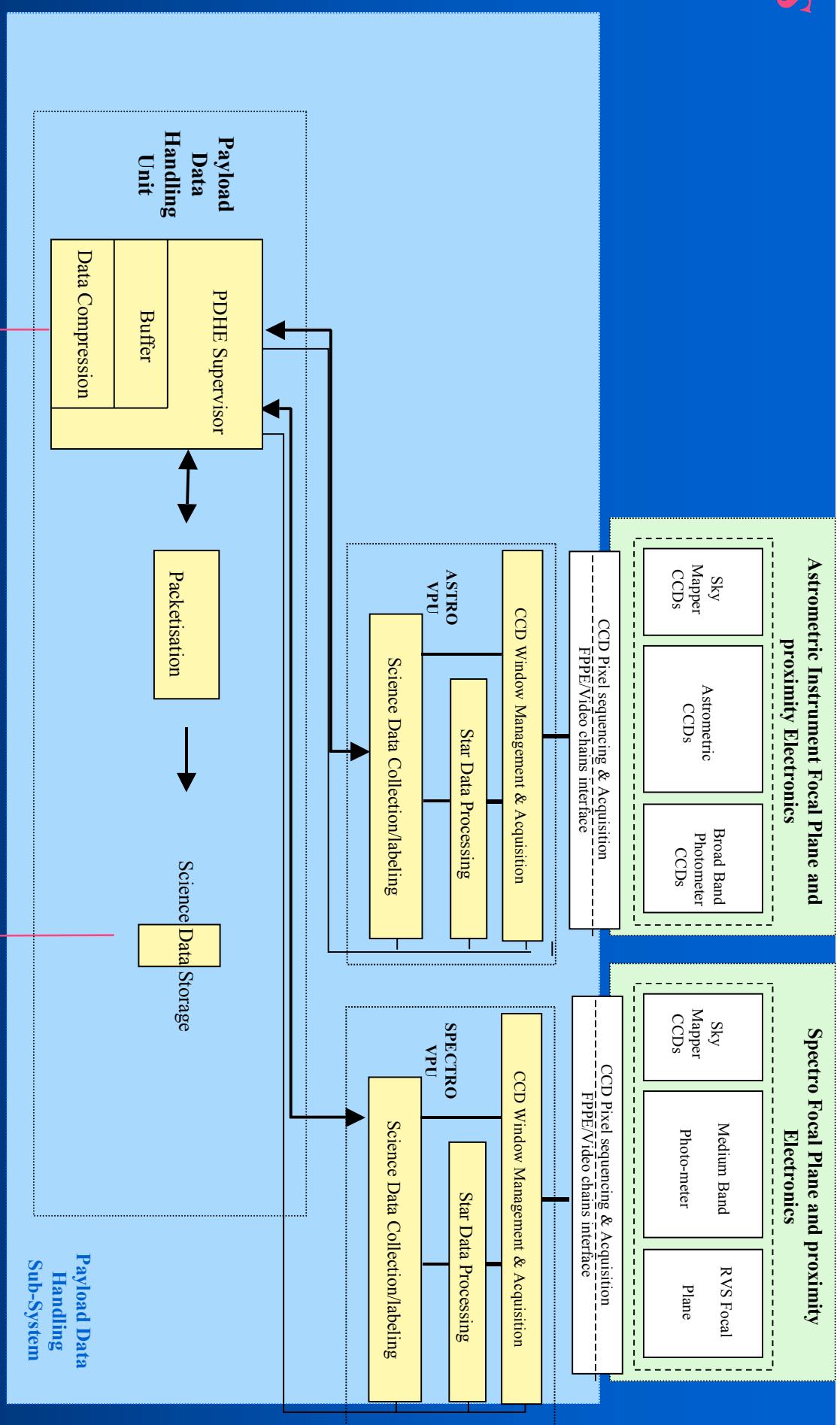
ASMO 1 2 3

AF01-16

17 BBP1-4

Simulations - Détection

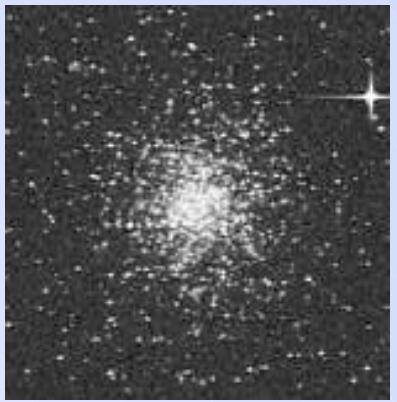
PDHS



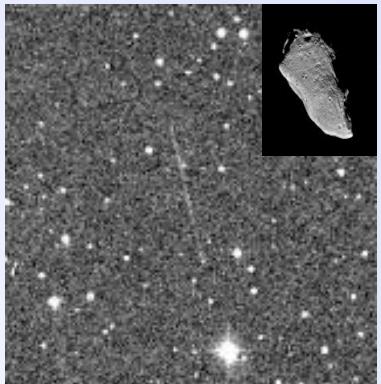
From W. Gasti

Radial Velocity Spectrometer
Workshop, 1/2 October, 2001

Various objects

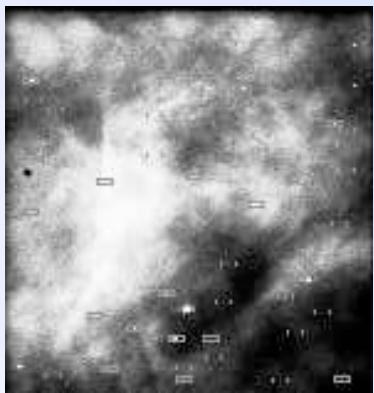


Globular cluster



Near-Earth Objects

High background



- Stars
 - High density
- NEO
 - Motion during integration
- Galaxies
 - Large area

On-Board Detection

□ 2 algorithms studied (APM, SWA)

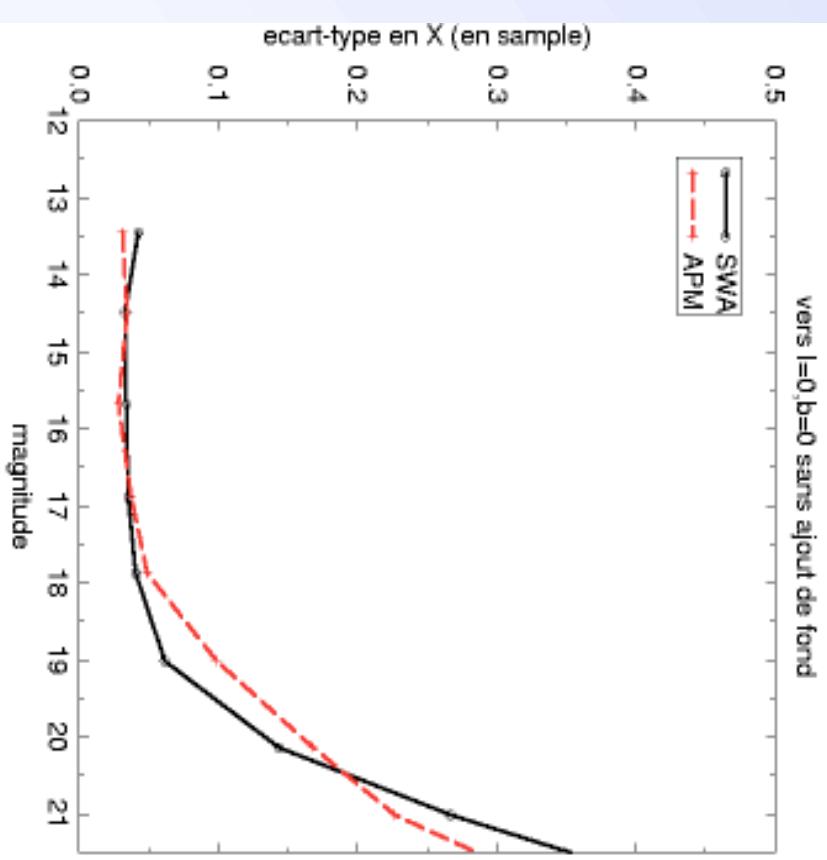
□ PDHE study

⇒ Needed ressources (CPU + memory)

⇒ C code needed

Based on:

- ⇒ OBD-CoCo-01 Work reference document
- ⇒ OBD-CoCo-02 Provisional software development



Detection - I: Basic outputs

- Sky background estimation
(local, global)
- Pre-processing
(filtering)
- Source search
(peak or pixel connectivity)
- Detection validation
(SNR)
- Parameter estimation
(position, flux, shape)
- Classification
(point-like, extended, binary)
- Scan rate computation

Detection - II: Requirements

- **Completeness**
 - > 20^m (ASM+SSM)
 - > 21^m for special objects (NEO/QSO/BD)
 - Galaxies and nebulae?
- **False detections**
 - No confirmation in SSM: higher SNR threshold level
 - Cosmic ray detection
- **Precision**
 - Good enough for object tracking
 - For scan rate
- **Classification**
- **Processing:** fast <2s (ASM), <3s (SSM), robust

Selection - I: Why and how

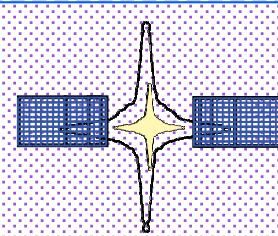
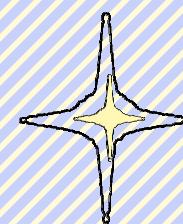
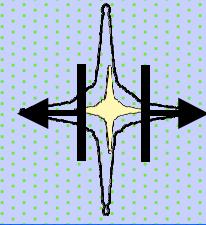
- After detection:
 - Which objects to observe
 - How (centring, size, overlapping, ...) in each CCD (tracking=observing strategy)
 - What to download
- Constraints on resources
 - Patches (limited number of)
 - Storage (possible downlink failure)
 - Telemetry (some great circles)
- For each object: a priority code
 - Can be as simple as magnitude
 - May depend on shape, field density, position...

Selection - II: Requirements

- Selection reproducible on ground (scientific censorship)
- On-board processing and transmission
 - No overlapping of samples
 - Limited number of patches
 - Lag between arriving objects
 - Limited on-board memory
 - Limited telemetry
- Observing strategy
 - Crowded fields, double stars, galaxies, NEO: TBD (e.g. GAIA-CUO-100)

Bright stars

ASMO ASM 1 ASM 2 ASM 3 AF 1



The same definition
for all windows

The space between
windows is
determined by the
comparison
between **ASM0**
and **ASM1**

No saturated samples
are downloaded

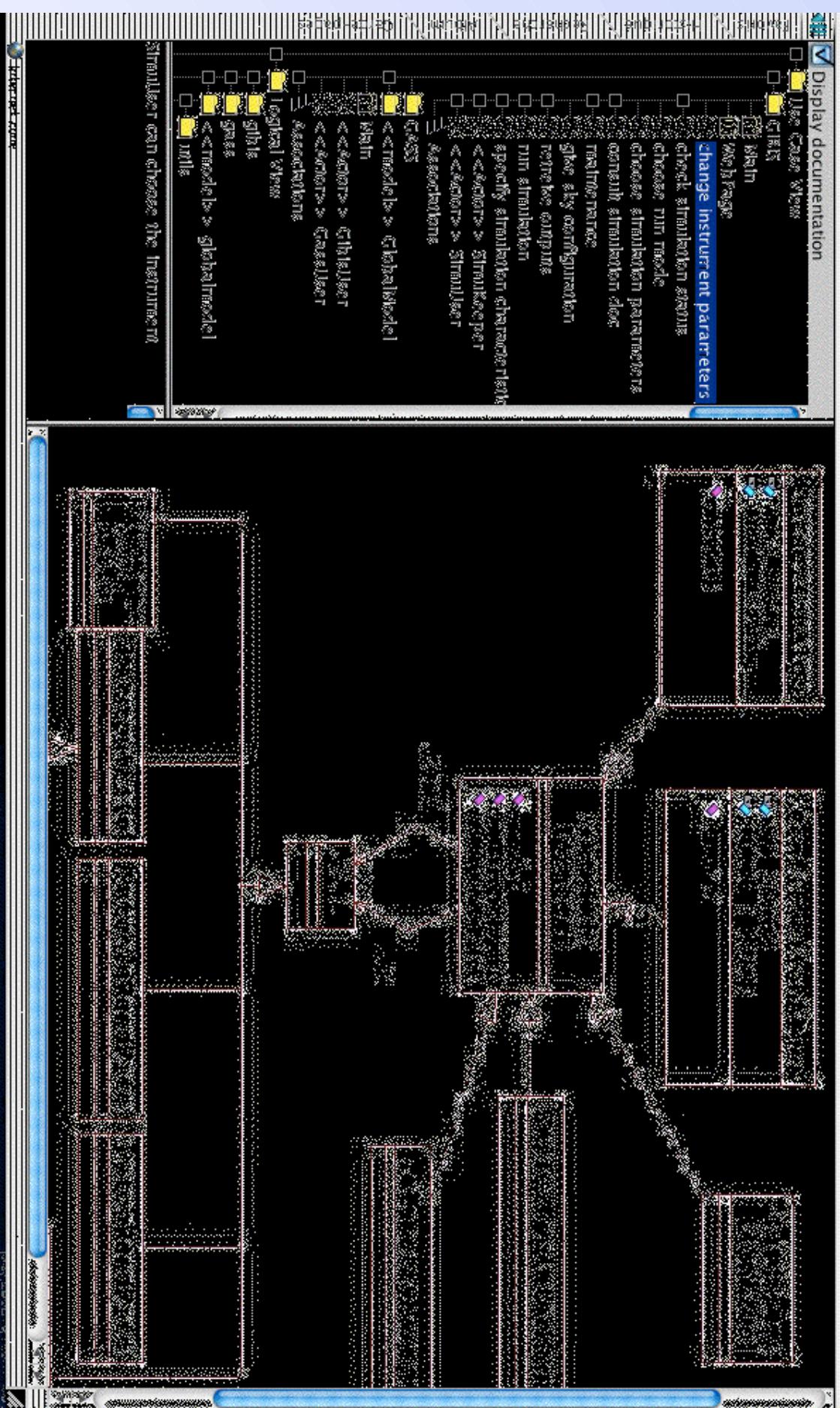
GAIA-CUO-100,
AAEB-FACB-01
GAIA-BCN-JP-001

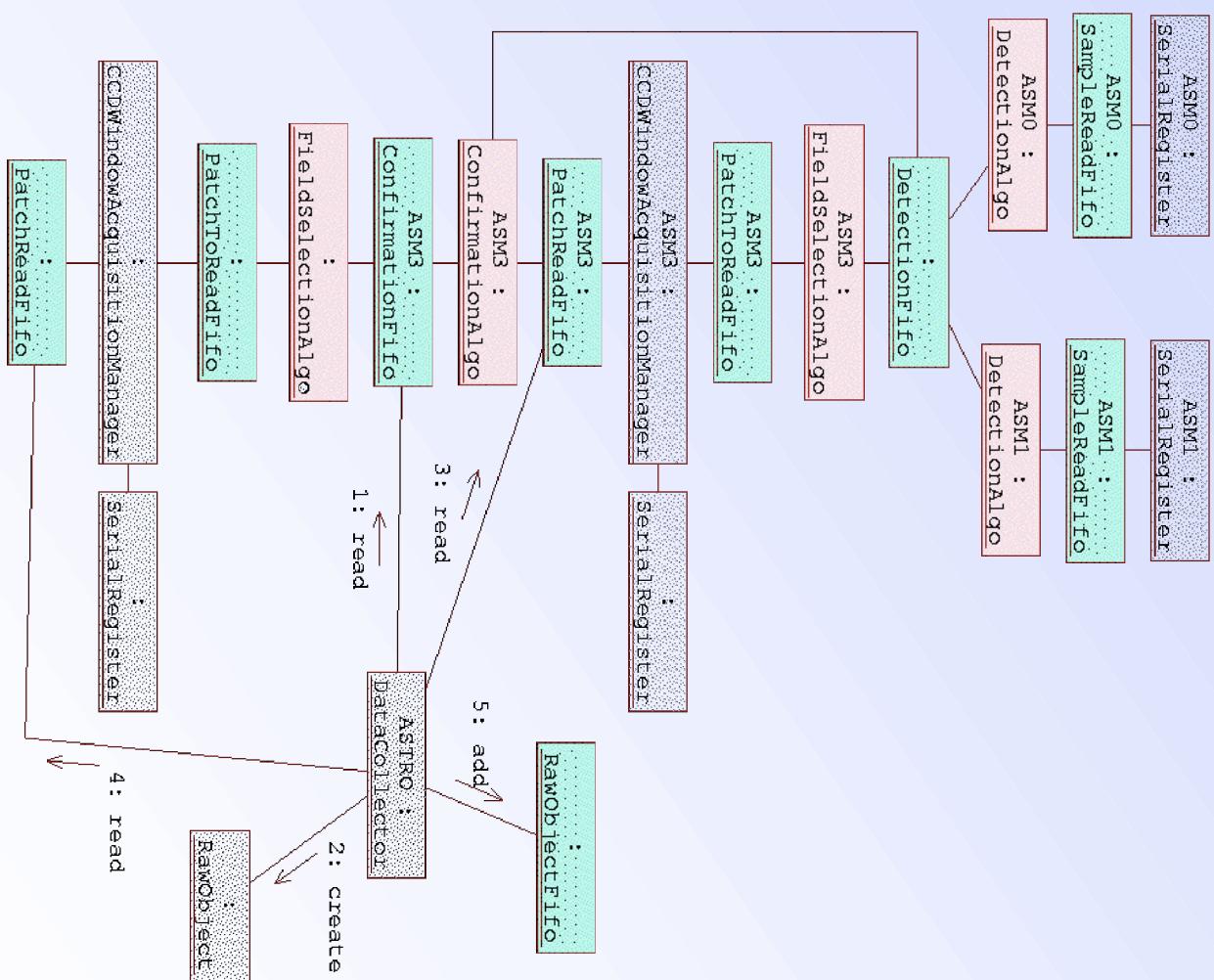


Simulations needed

- All sources
 - stars, binaries, galaxies, solar system objects
 - mean statistical distributions of the parameters
 - extreme cases
- Sky configurations
 - crowding
 - high background variations
- Instrument
 - precise PSF estimation
 - cosmic rays
 - CTE degradation

Rose model





PDHS

PDHS demonstrator

